

Young Researchers Seminar 2009

Torino, Italy, 3 to 5 June 2009

Measurement of variability involved in the car-following rules



Aurélien Duret
Aurelien.Duret@entpe.fr



Context

- Empirical evidence = traffic stream is **heterogeneous**
- Developpement of **microscopic models**
- ➔ **Need to know the driver's behavior distribution**
- ➔ **Need some microscopic data (trajectories)**

Measurement of variability involved in the car-following rules

Introduction

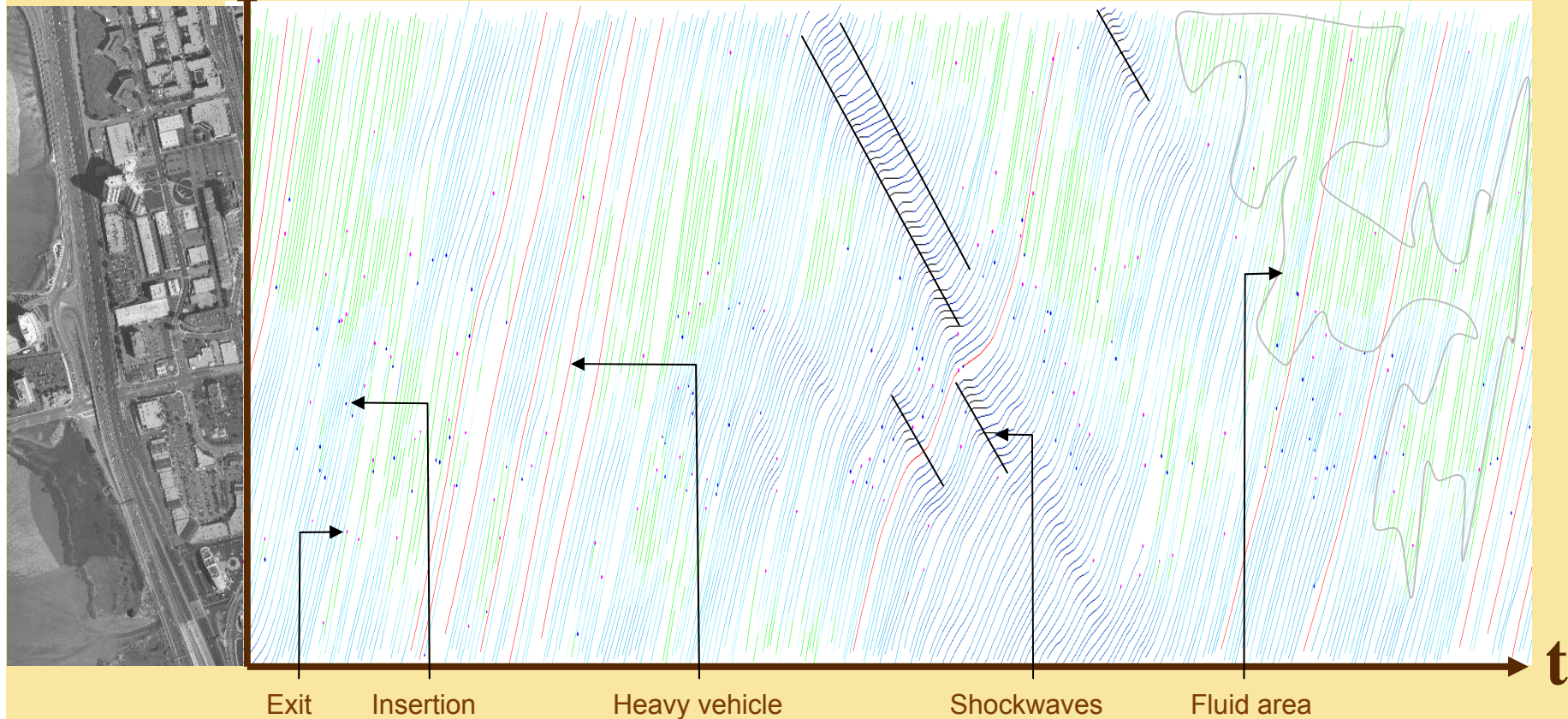
Methodology

Data

Results

I80, USA

(NGSIM Program)



Identification

Geometric characteristics

Trajectory

Surrounding conditions

Lane Id
Vehicle Id

Class /Length
Vehicle width

Position
Time

Leader Id
Follower Id

Car-following model



$(i+1)$



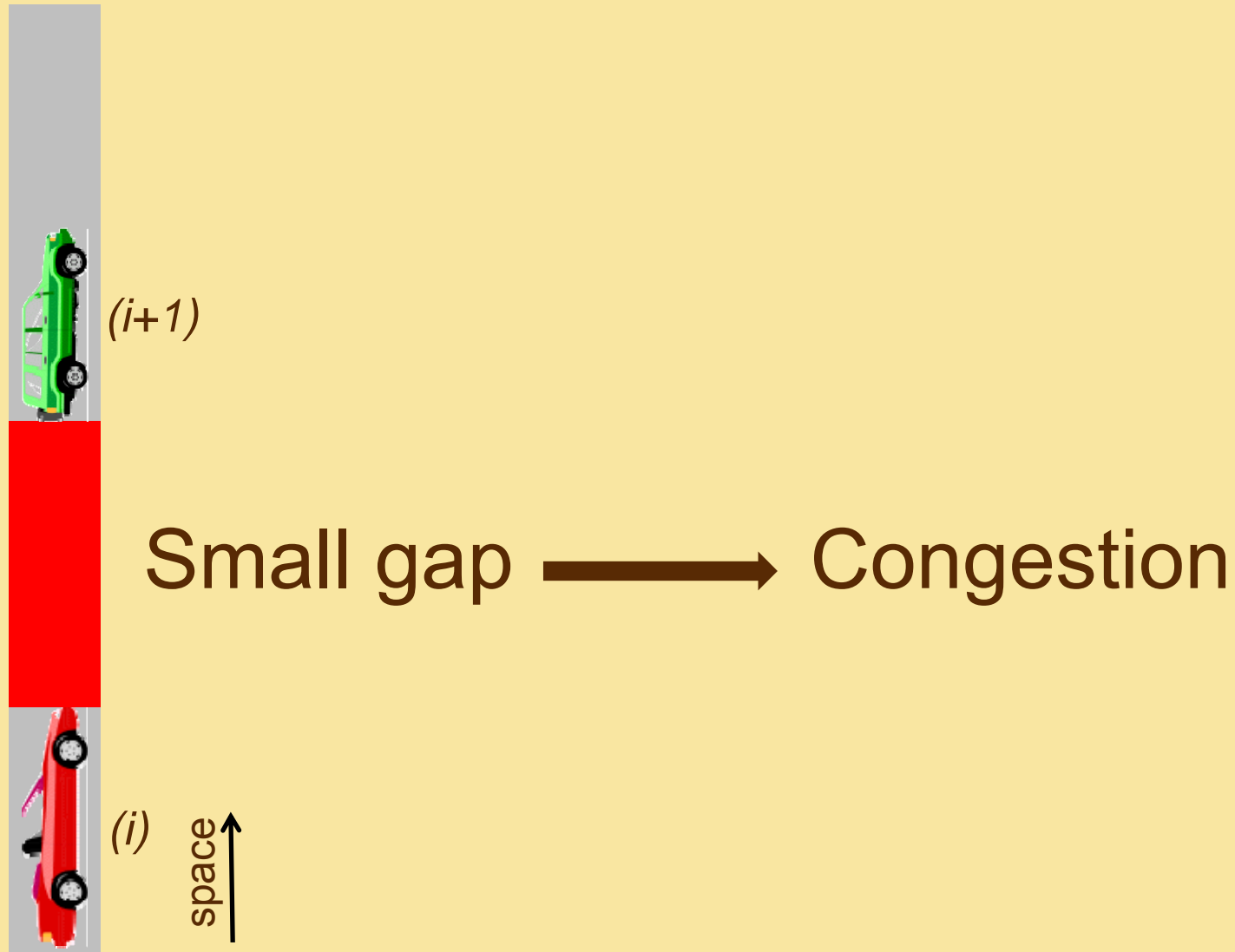
Large gap \longrightarrow free-flow



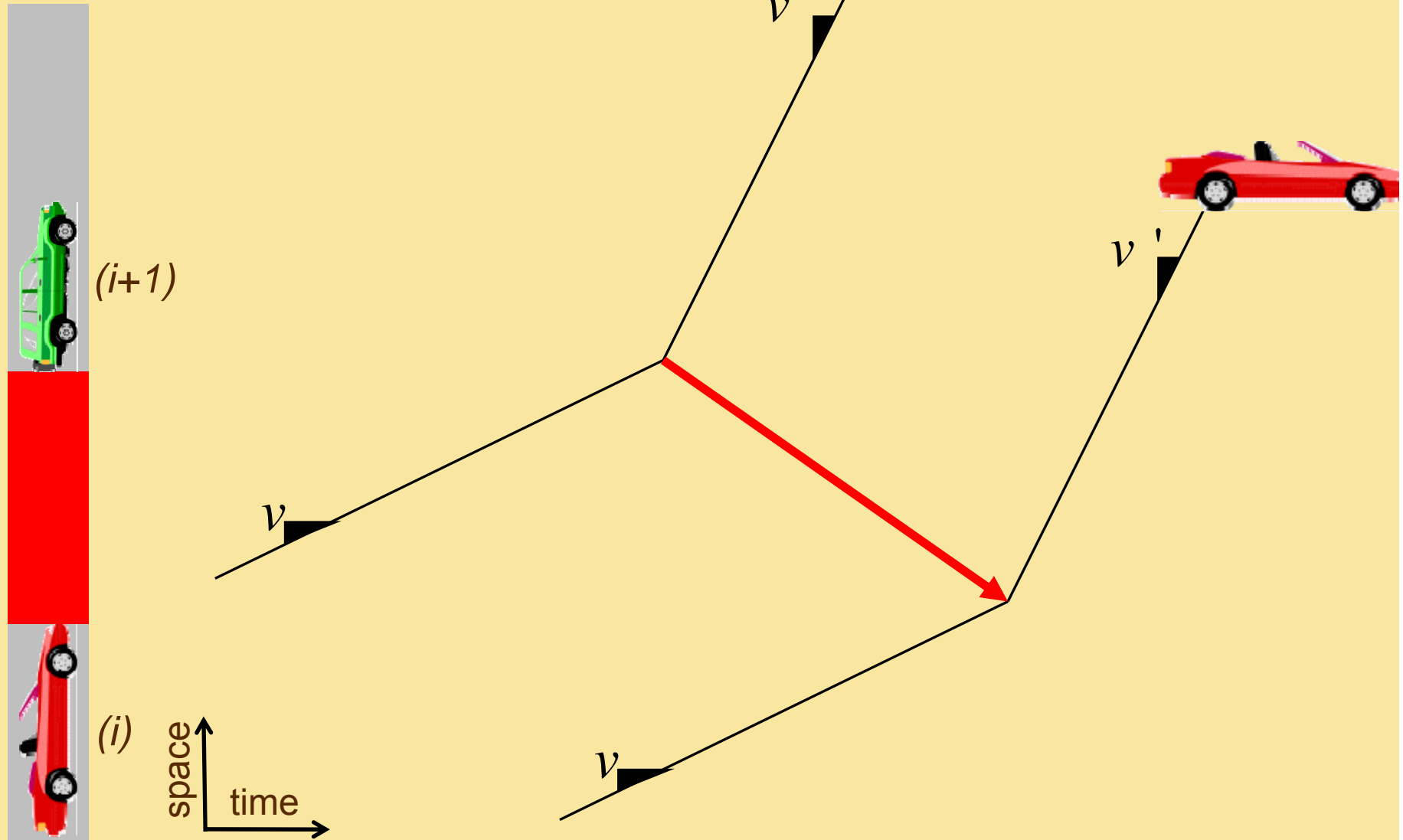
(i)



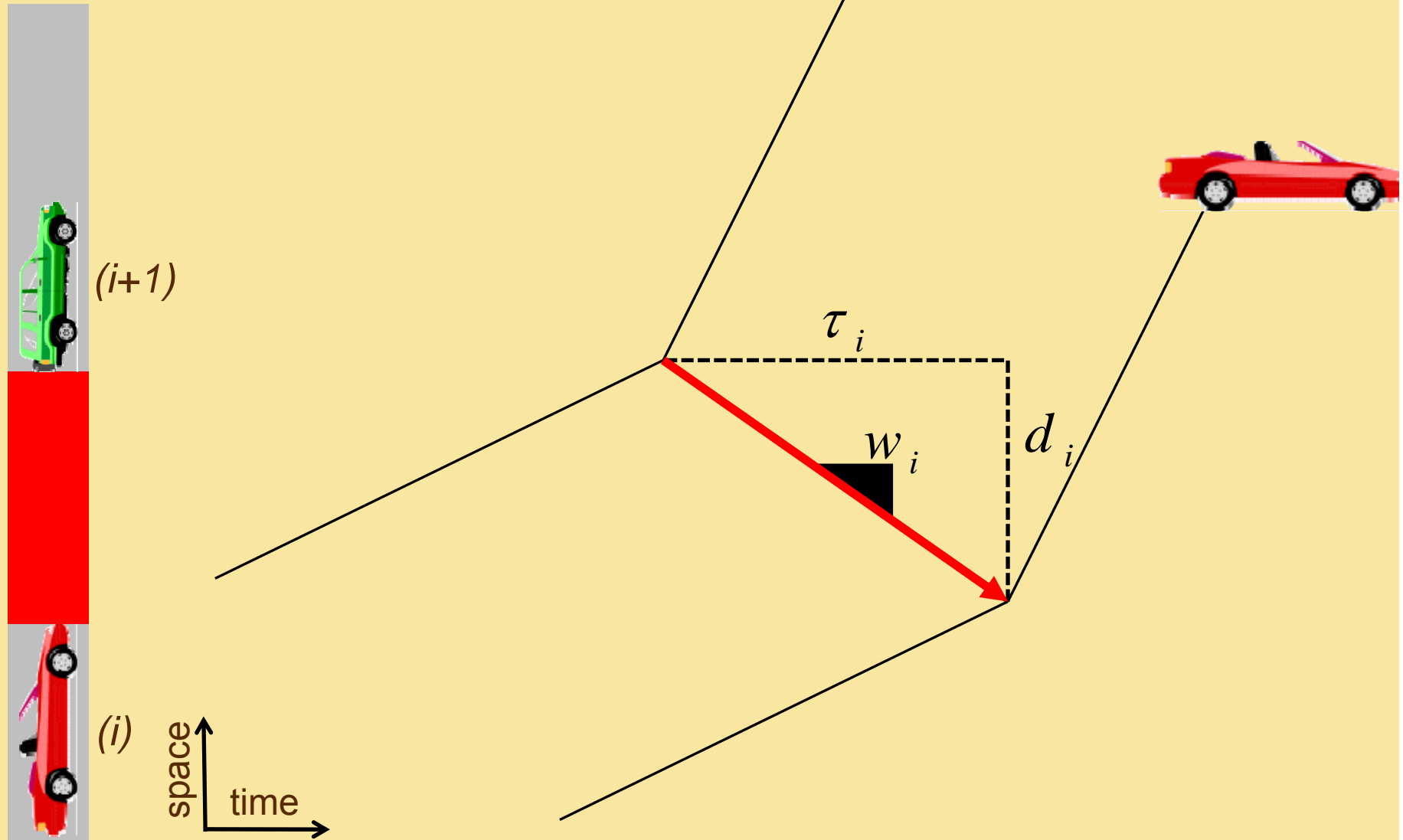
Car-following model



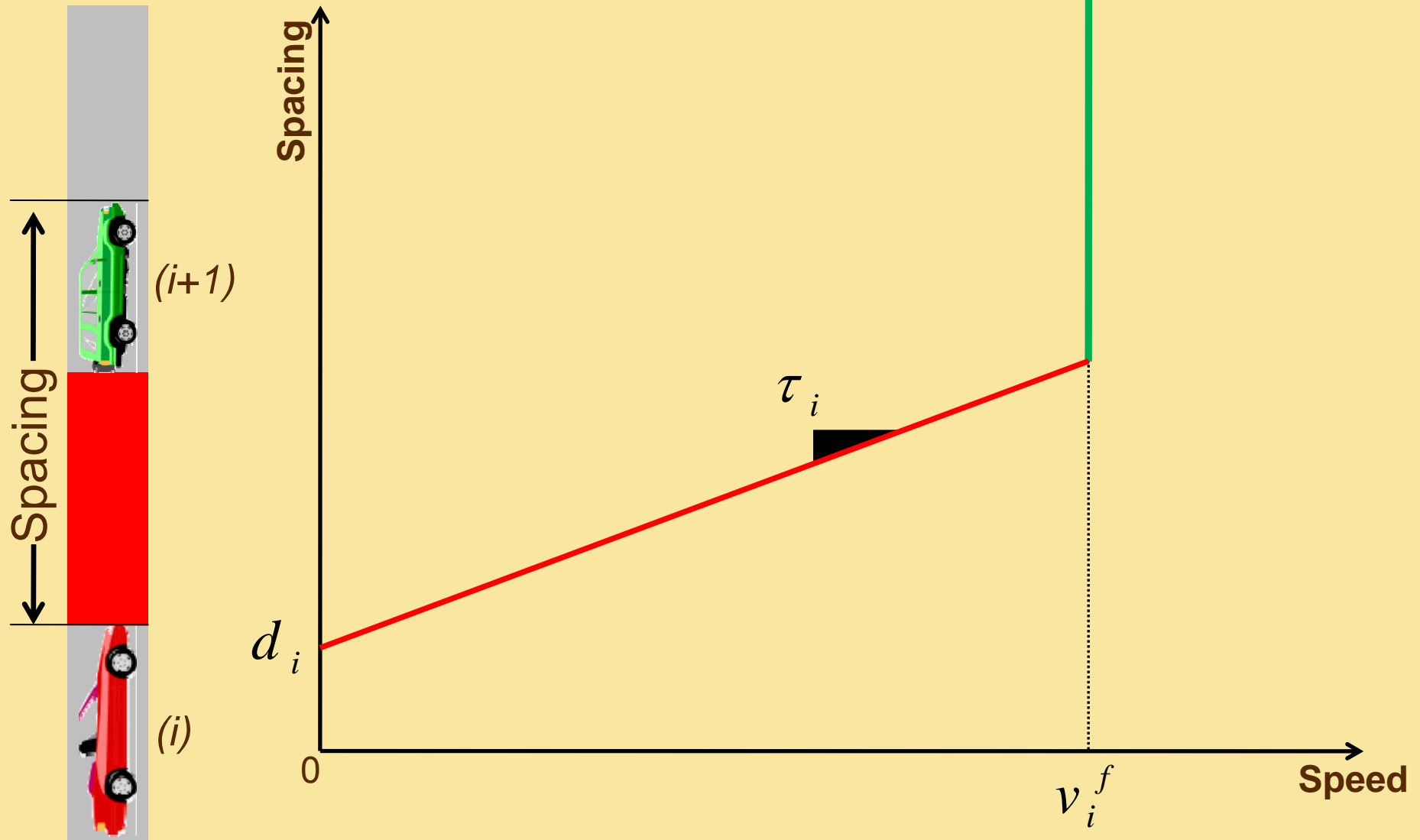
Car-following model



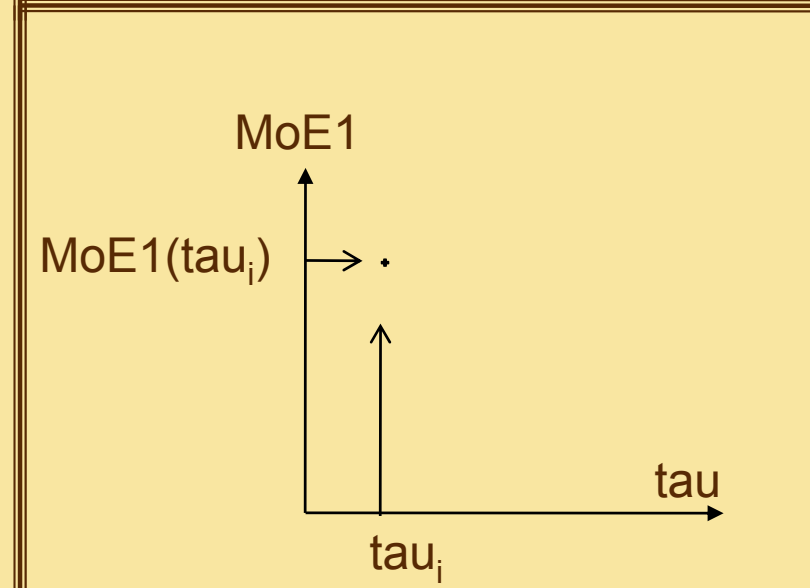
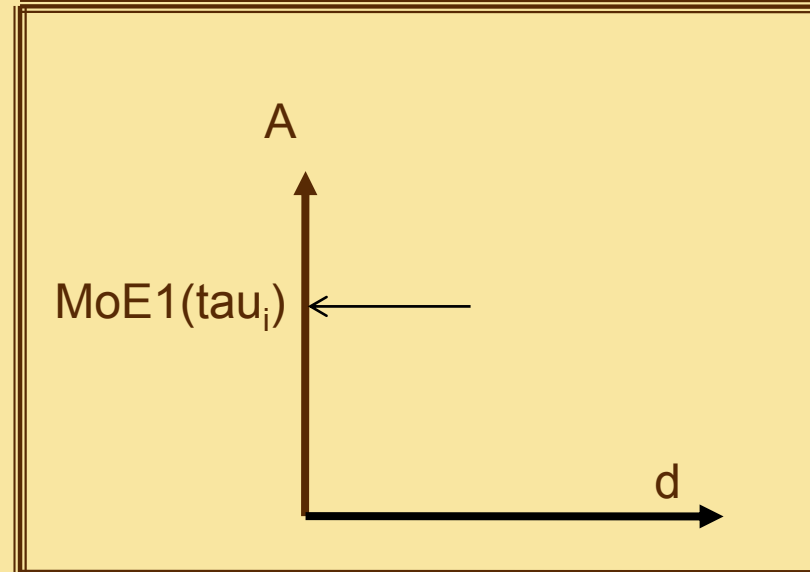
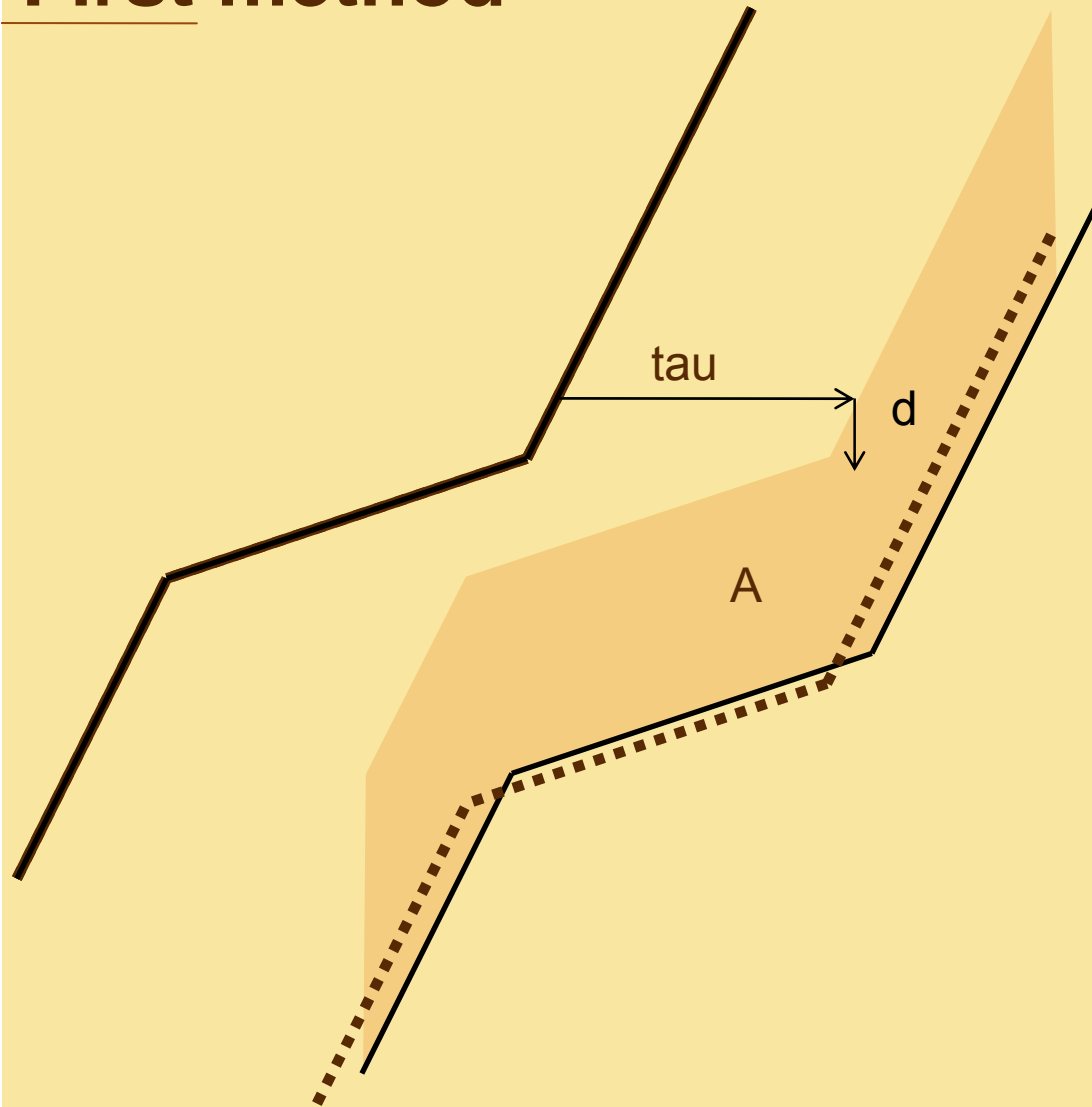
Car-following model



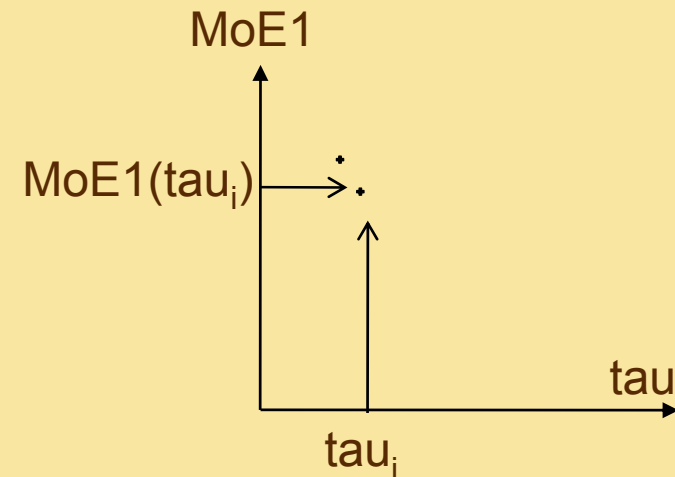
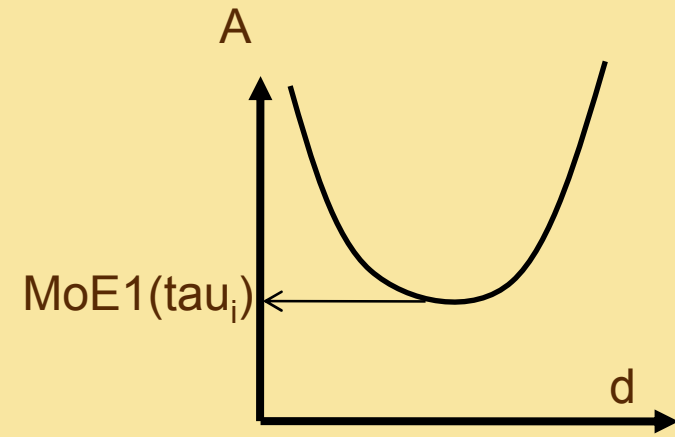
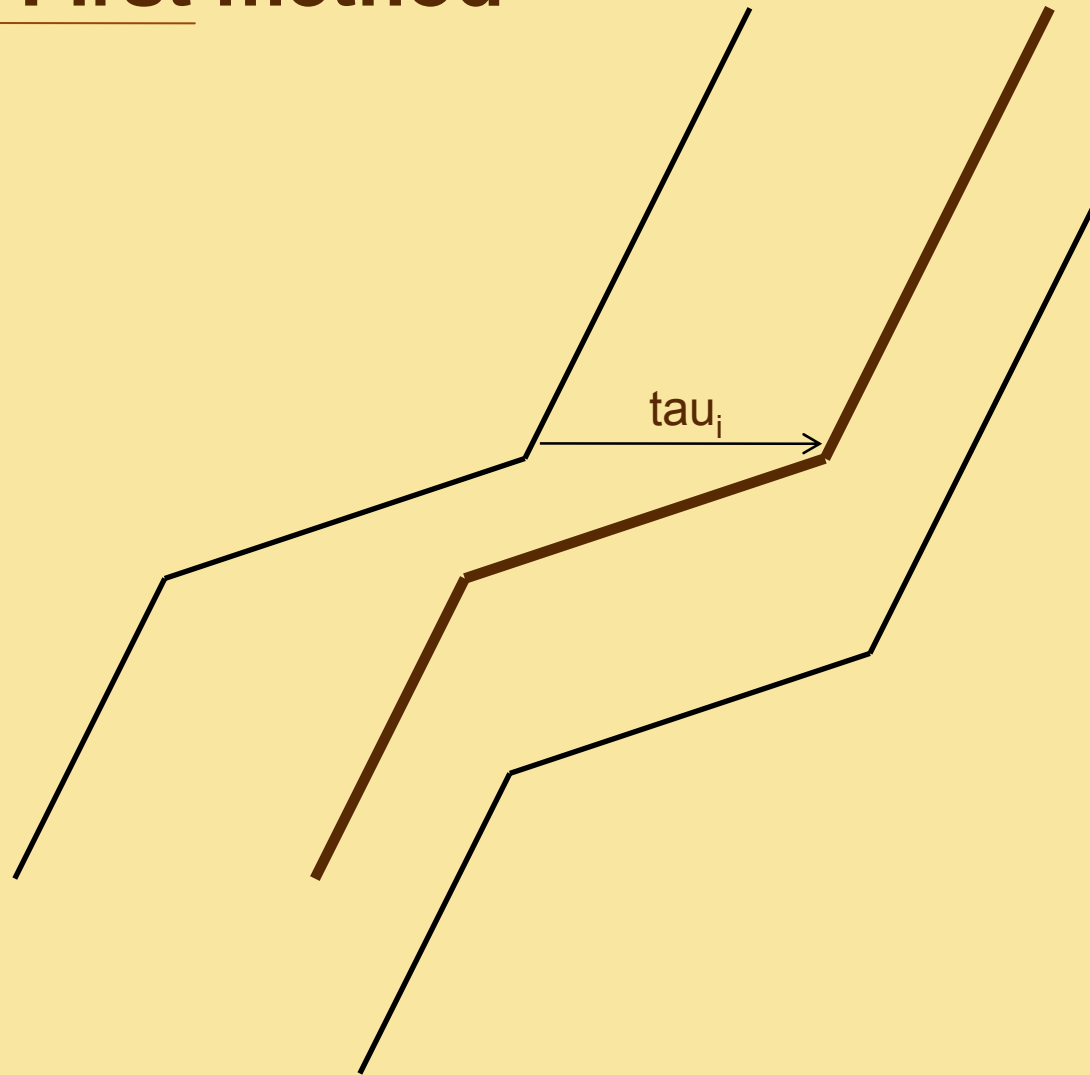
NEWELL Car-following model



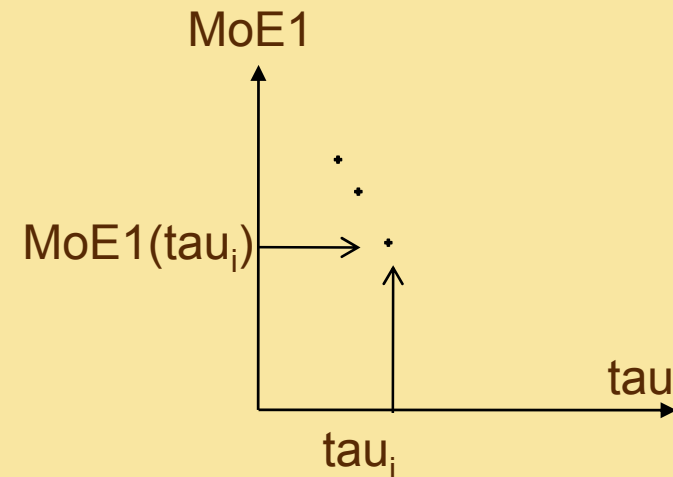
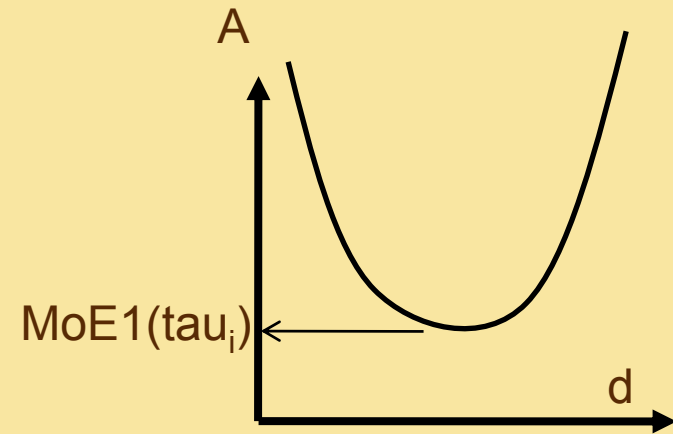
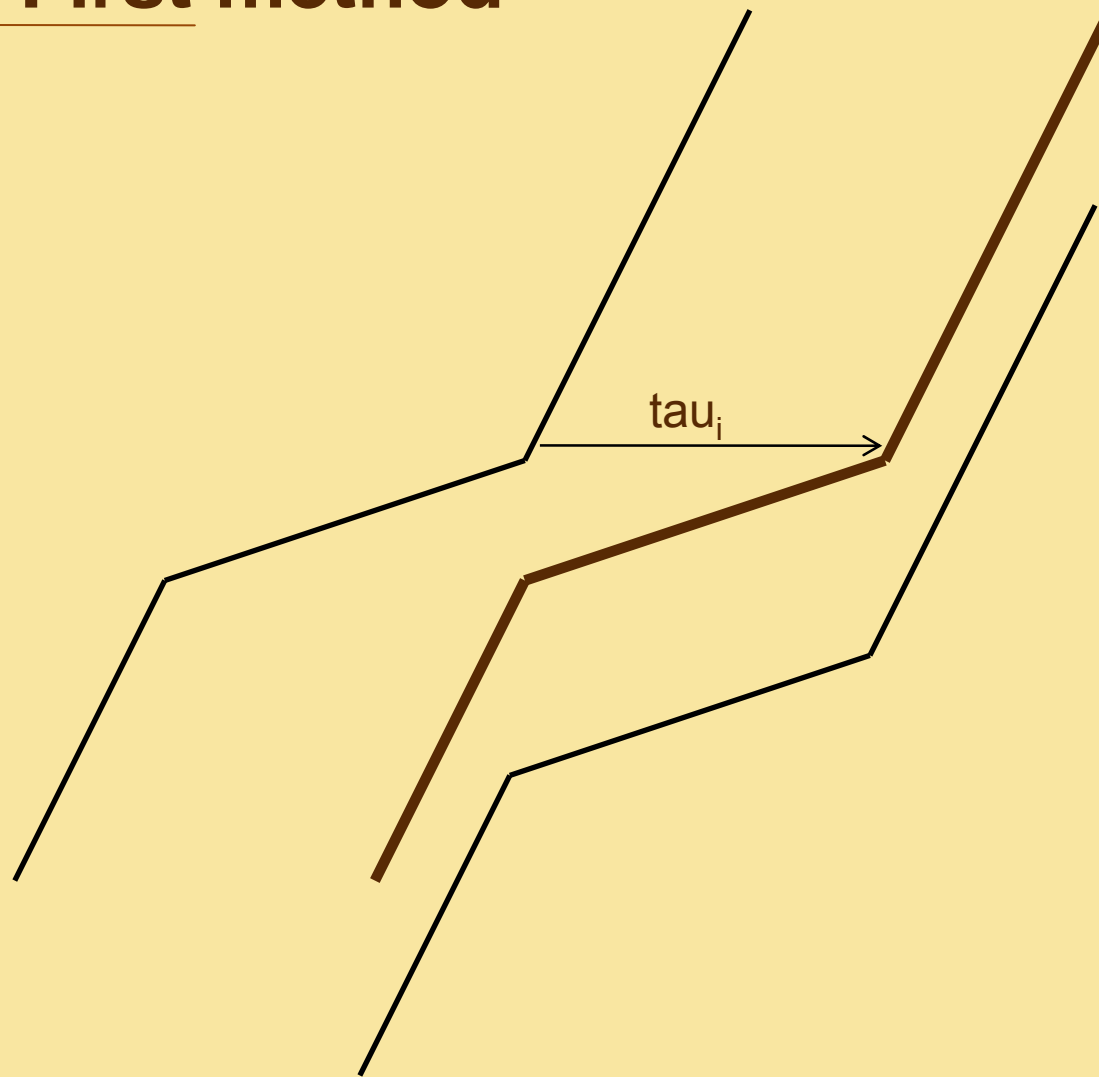
First method



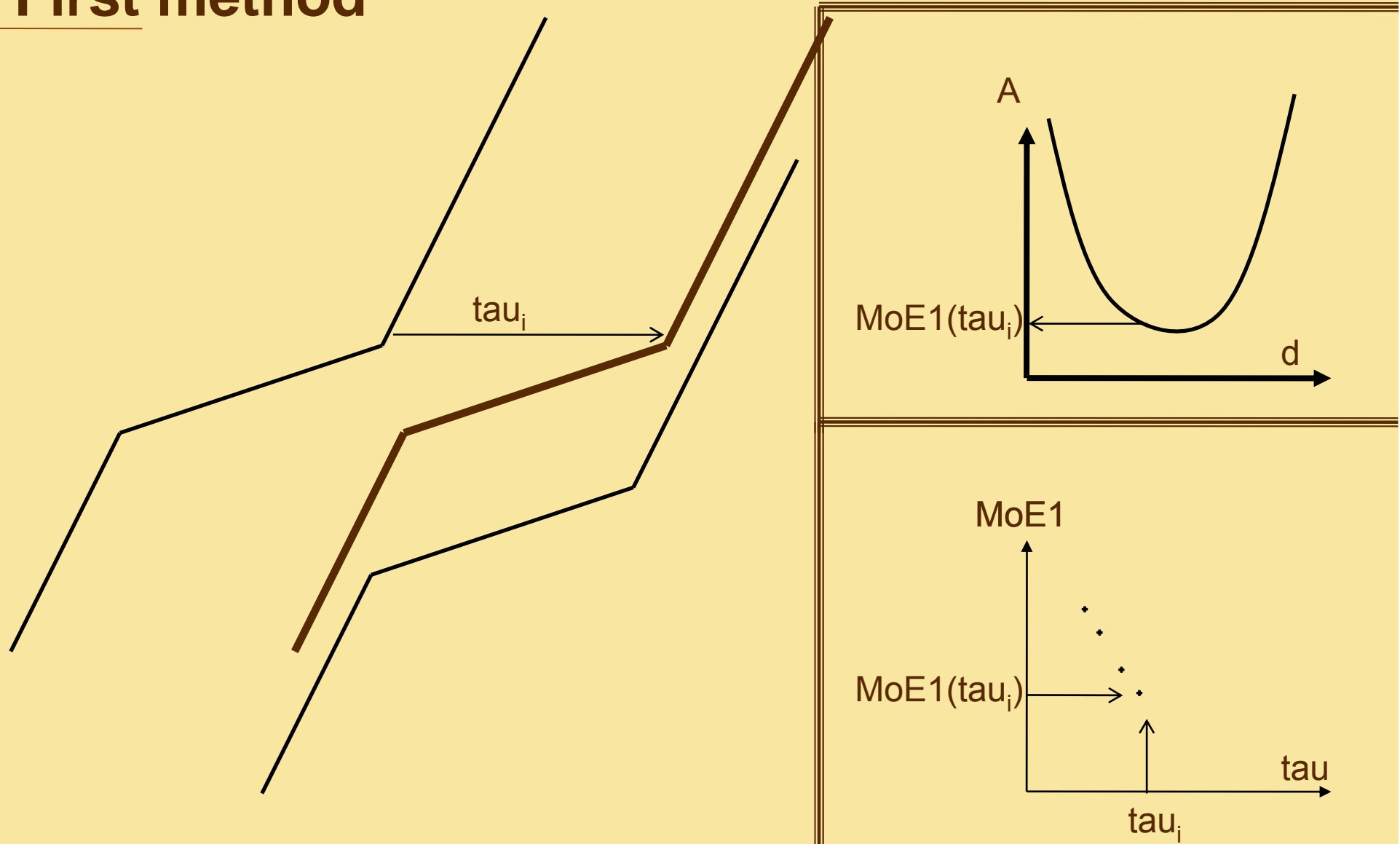
First method



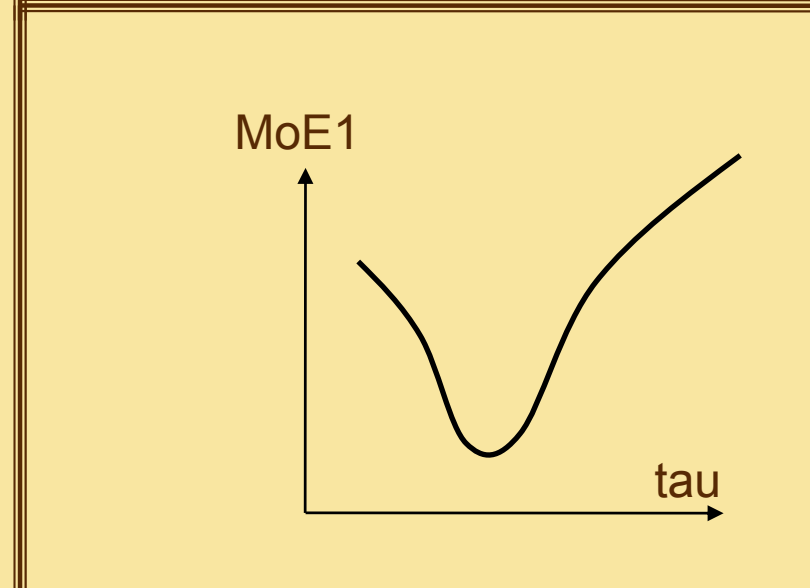
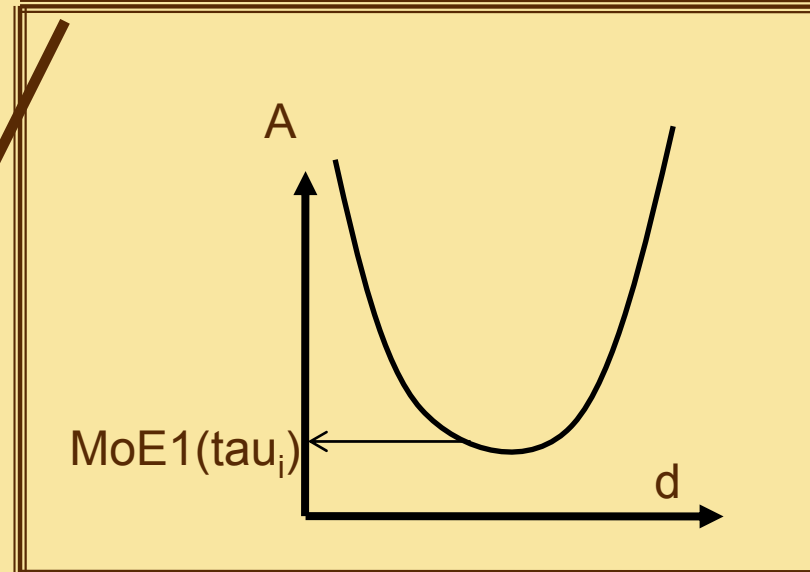
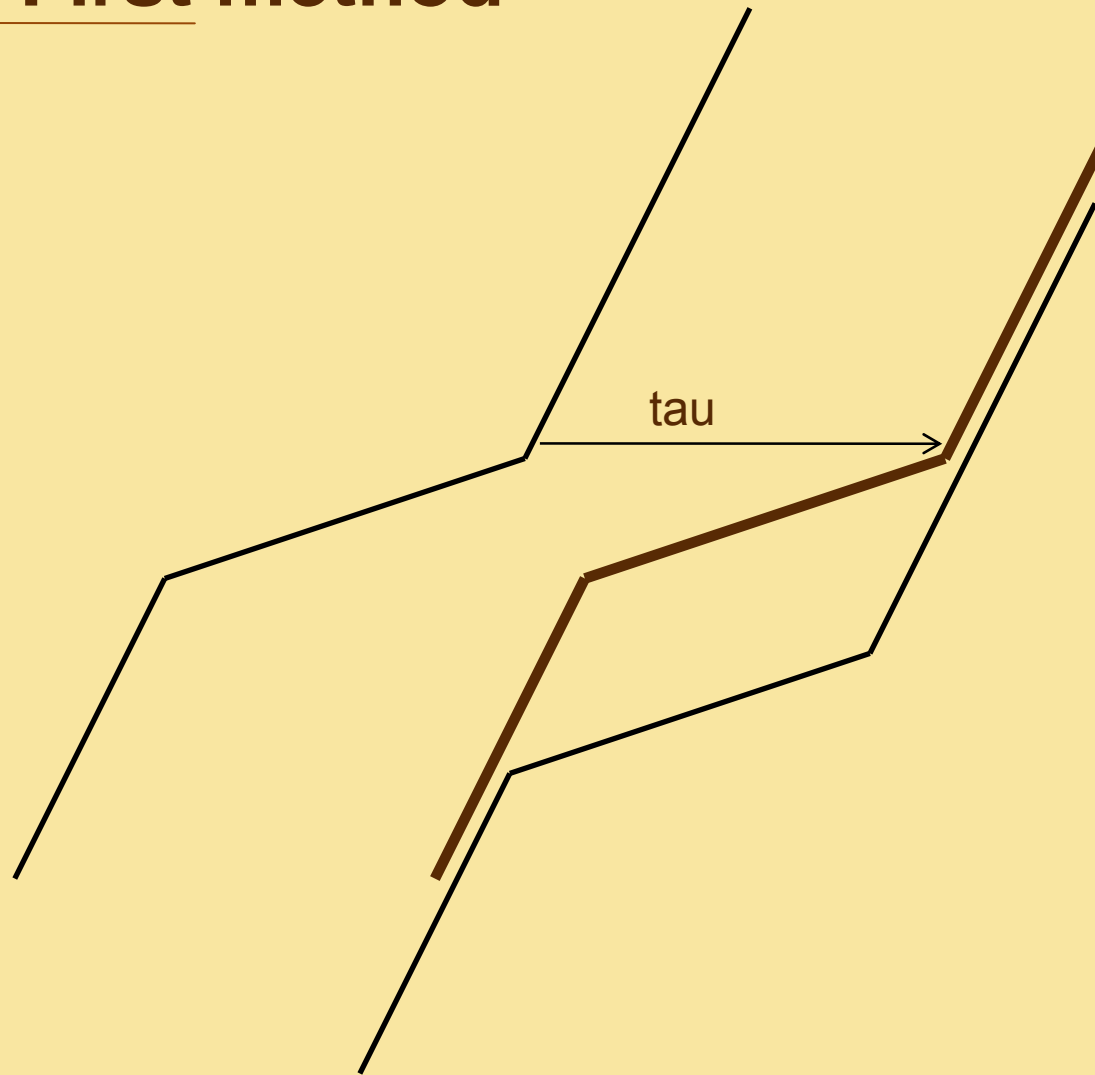
First method



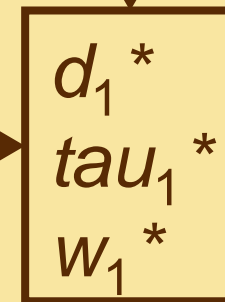
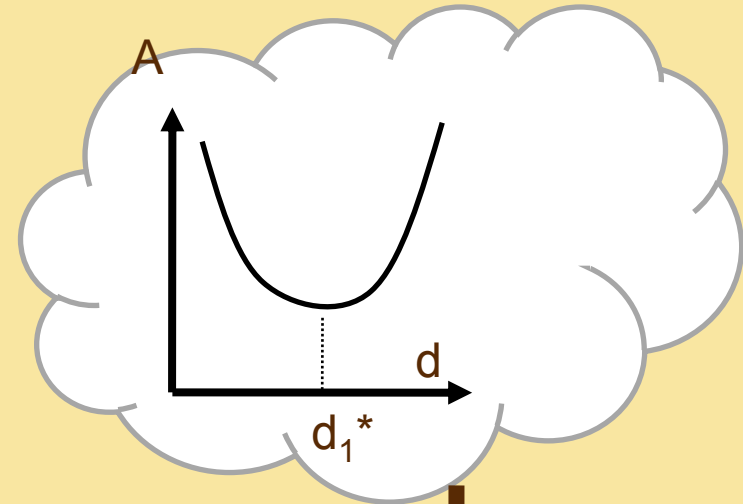
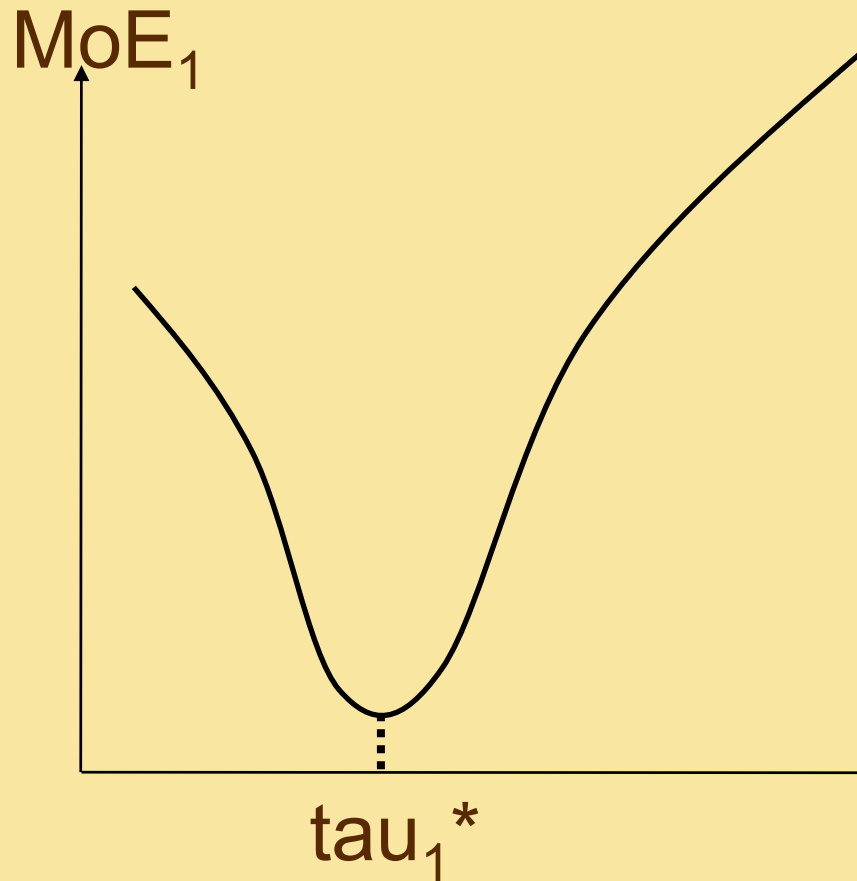
First method



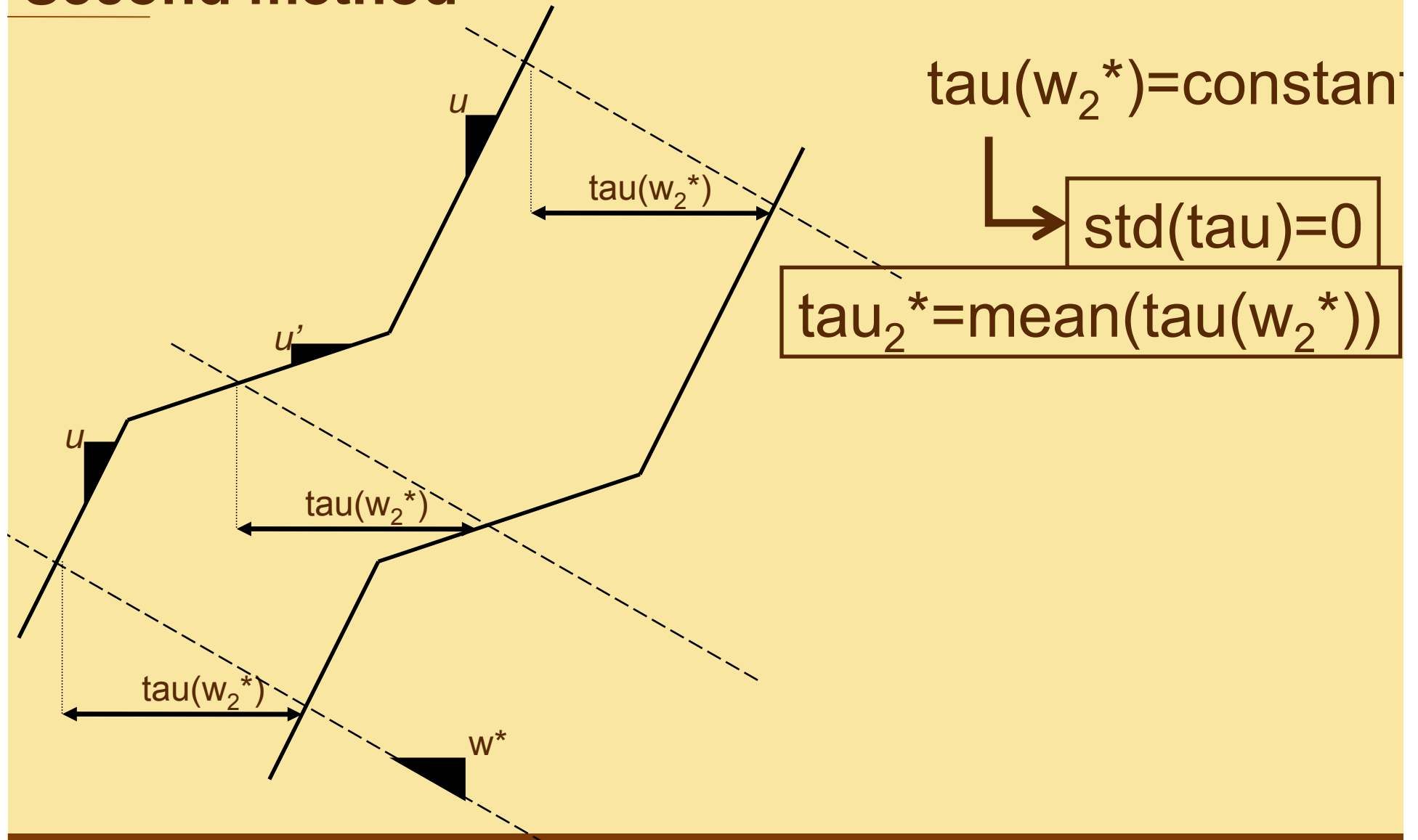
First method



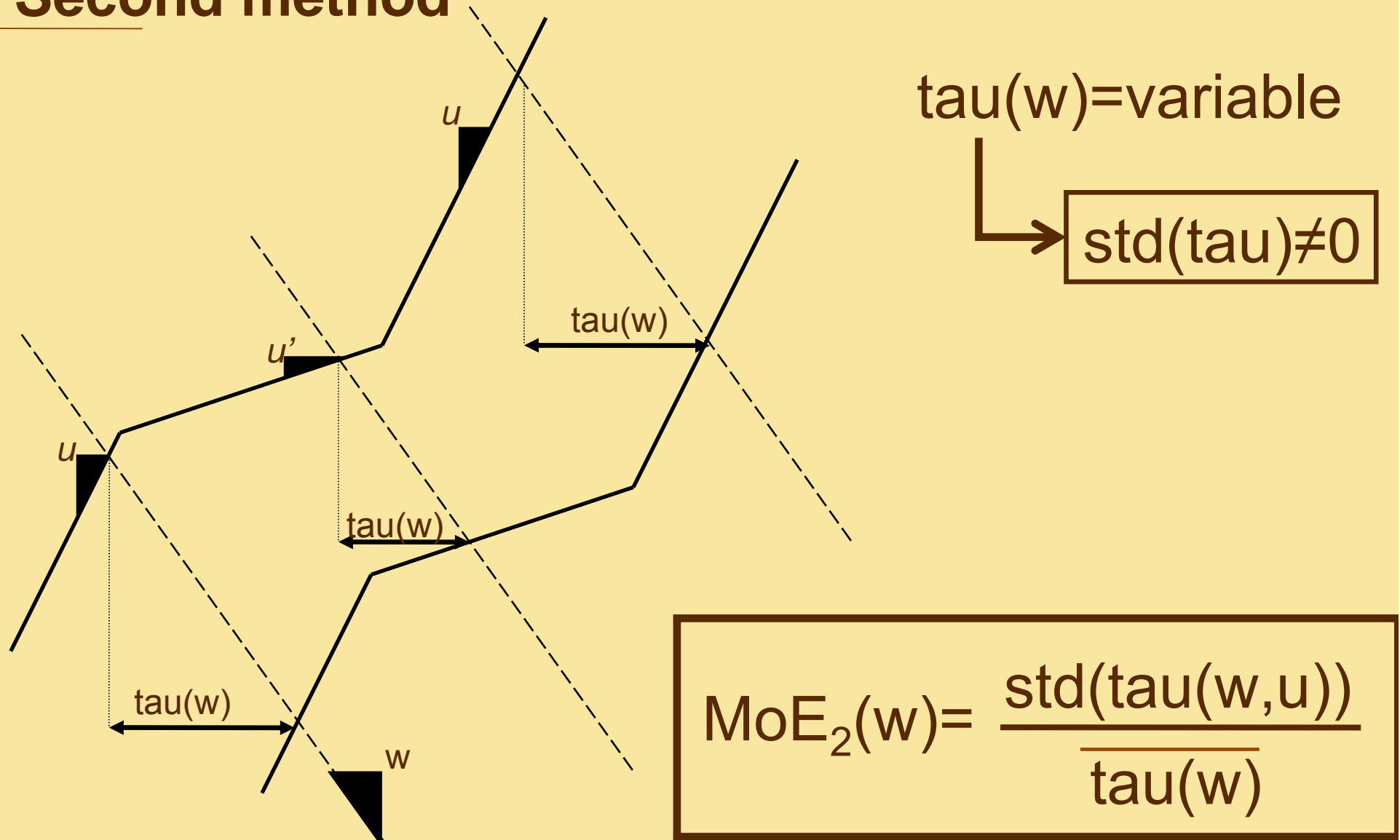
First method



Second method

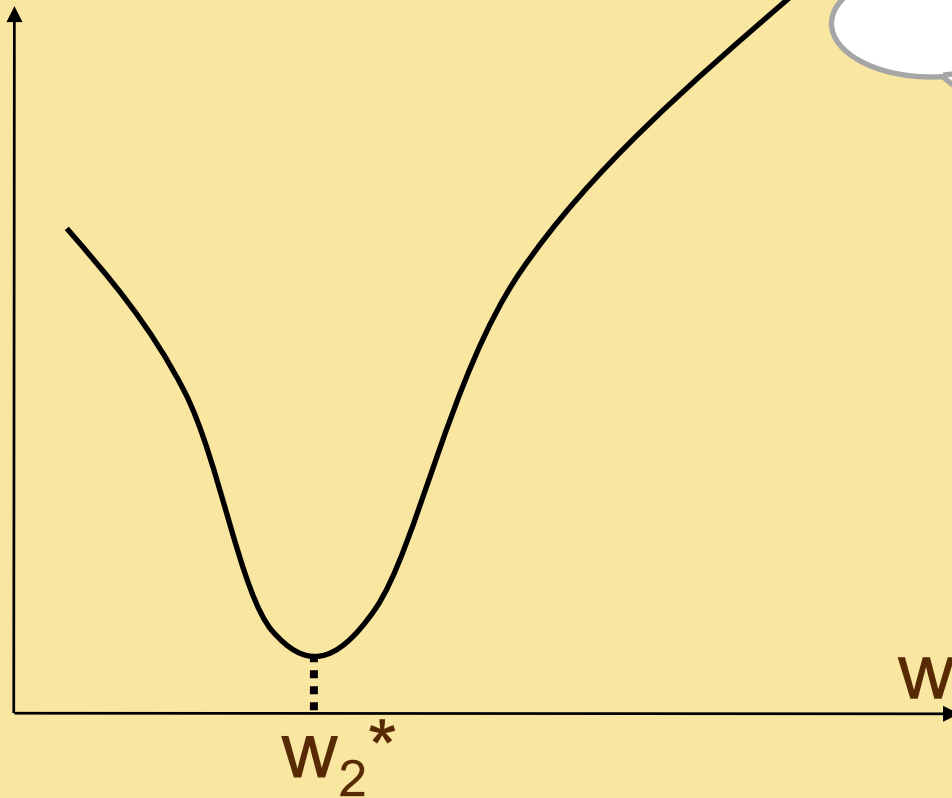


Second method



Second method

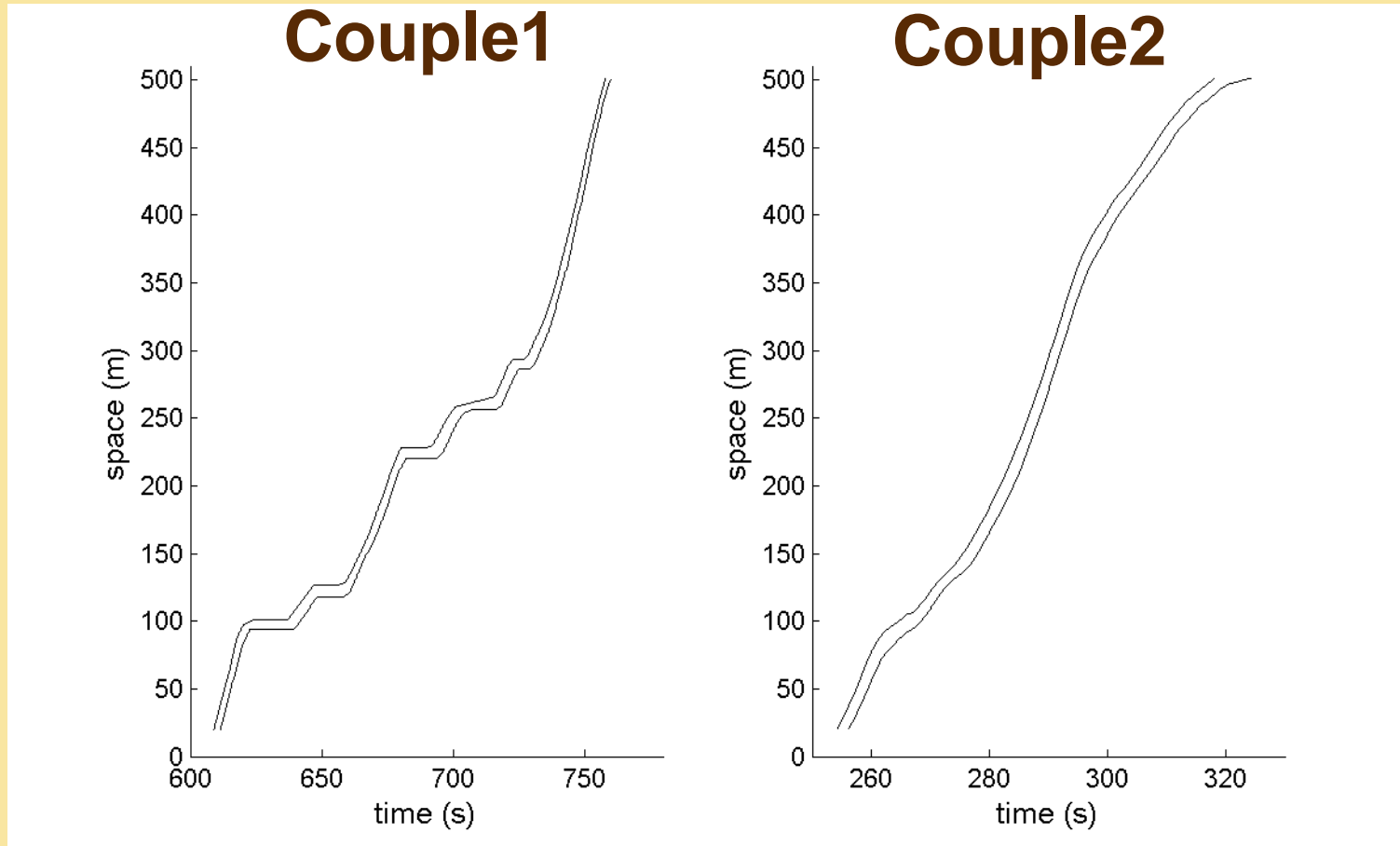
MoE



$$\tau_{2}^{*} = \text{mean}(\tau(w_{2}^{*}))$$

d_{2}^{*}
 τ_{2}^{*}
 w_{2}^{*}

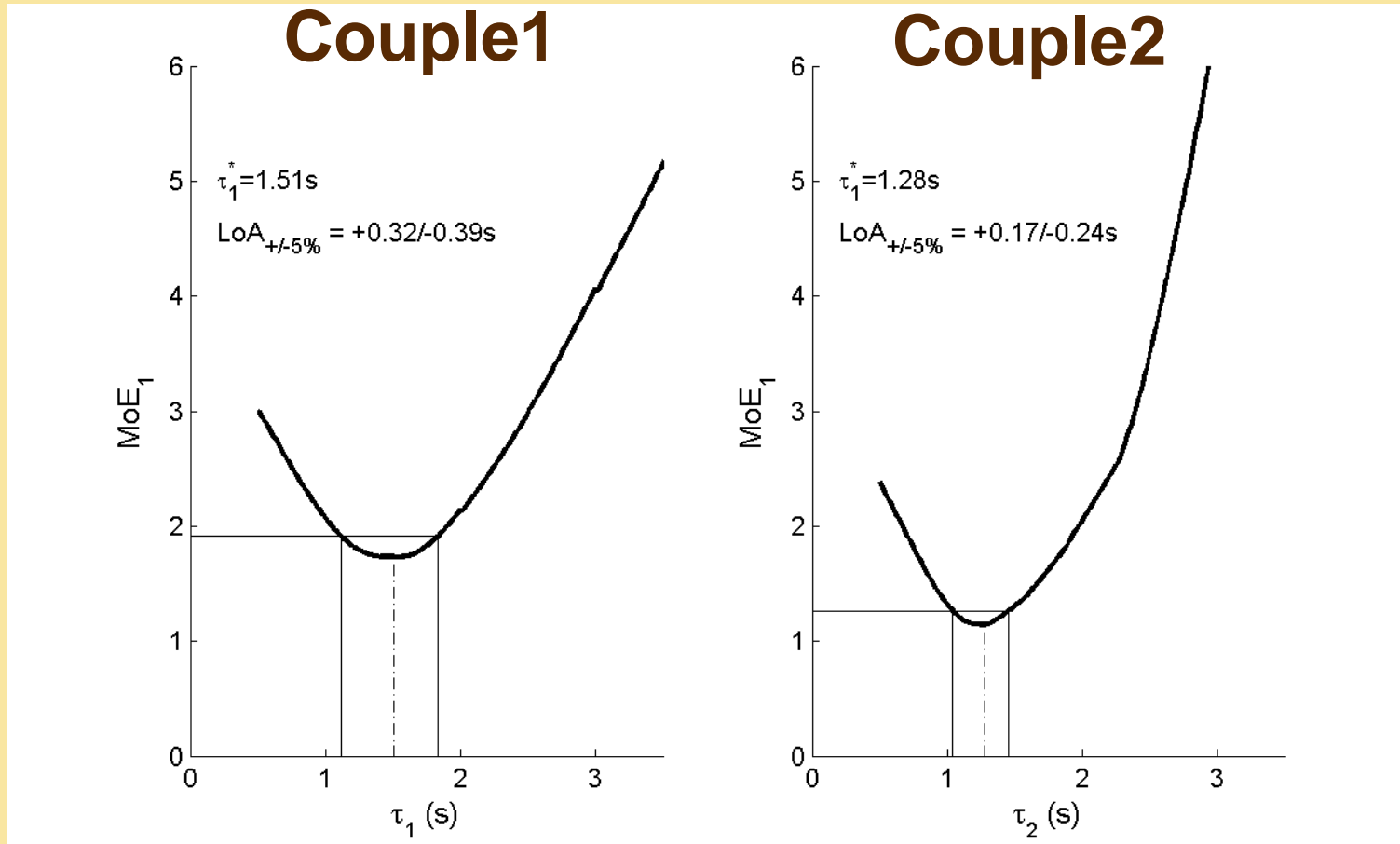
Two pairs of trajectories



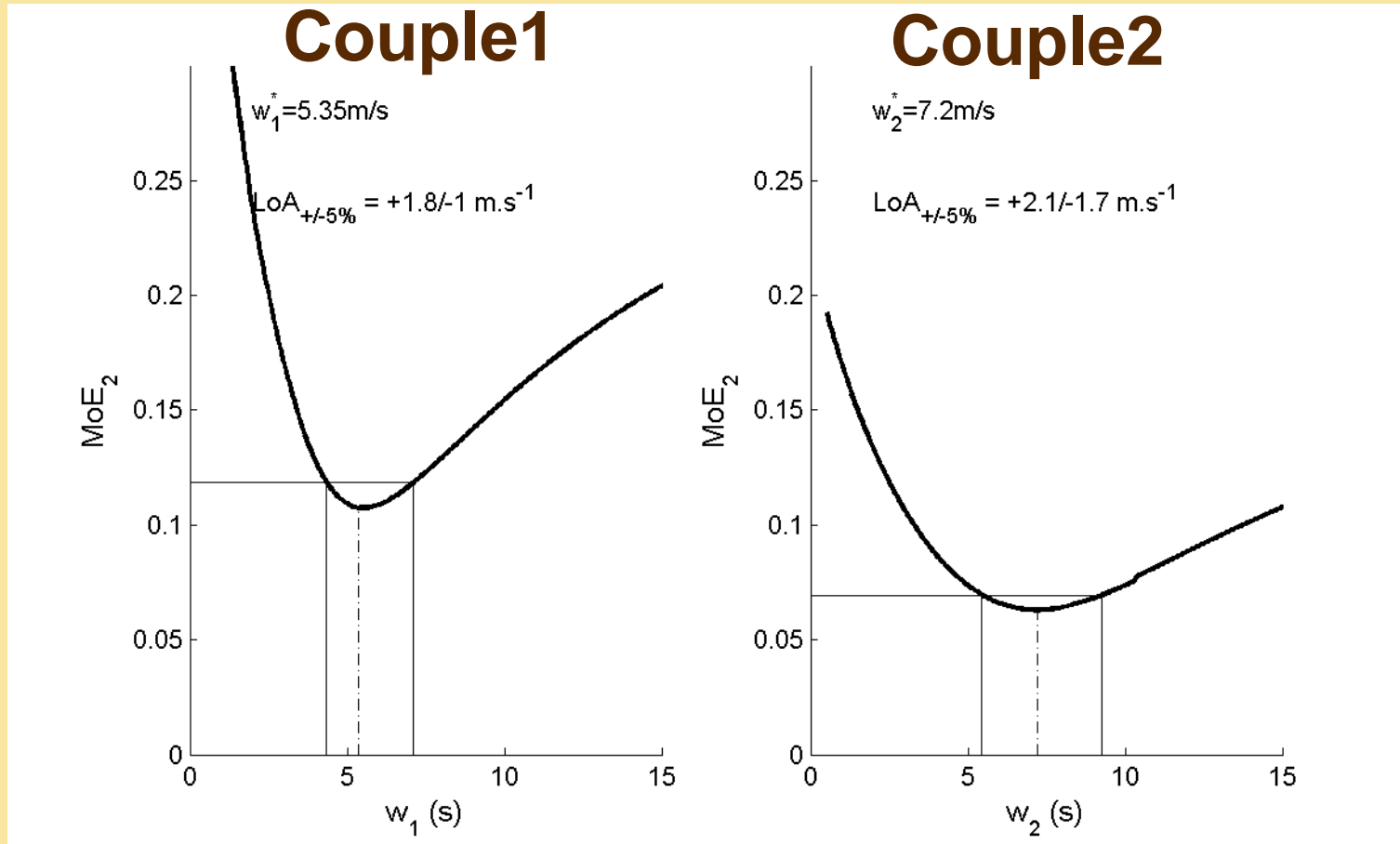
- 5 stop-&-go shockwaves
- Travel time : 150s

- No stop-&-go shockwave
- Travel time : 65s

MoE1



MoE2



Measurement of variability involved in the car-following rules

Introduction

Methodology

Data

Results

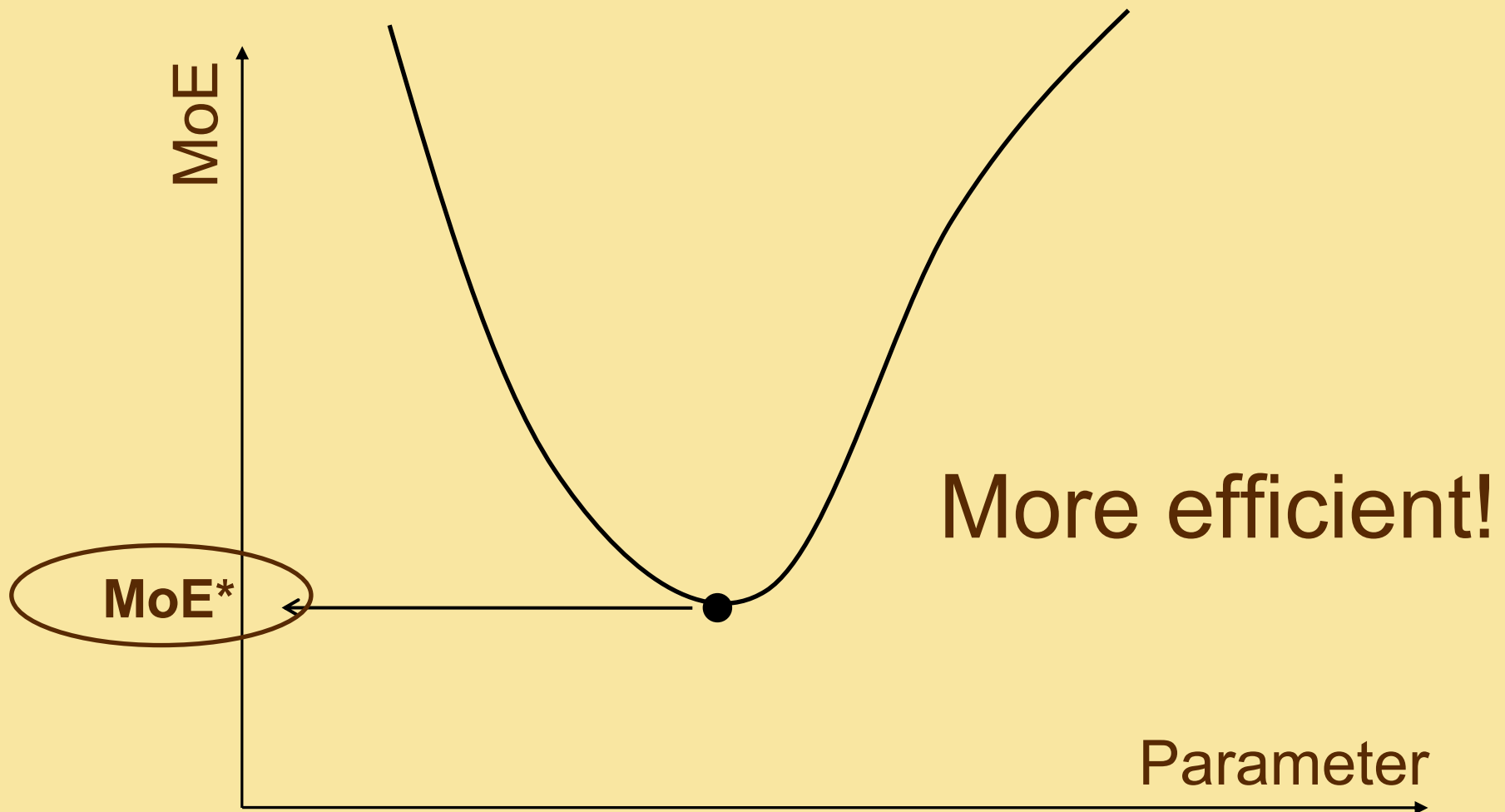
MoE1 & MoE2

	Couple1			Couple2		
	d_1^*	τ_1^*	w_1^*	d_2^*	τ_2^*	w_2^*
First method	7.4	1.6	4.8	7.8	1.2	7.2
Second method	7.6	1.4	5.3	8.5	1.2	6.2

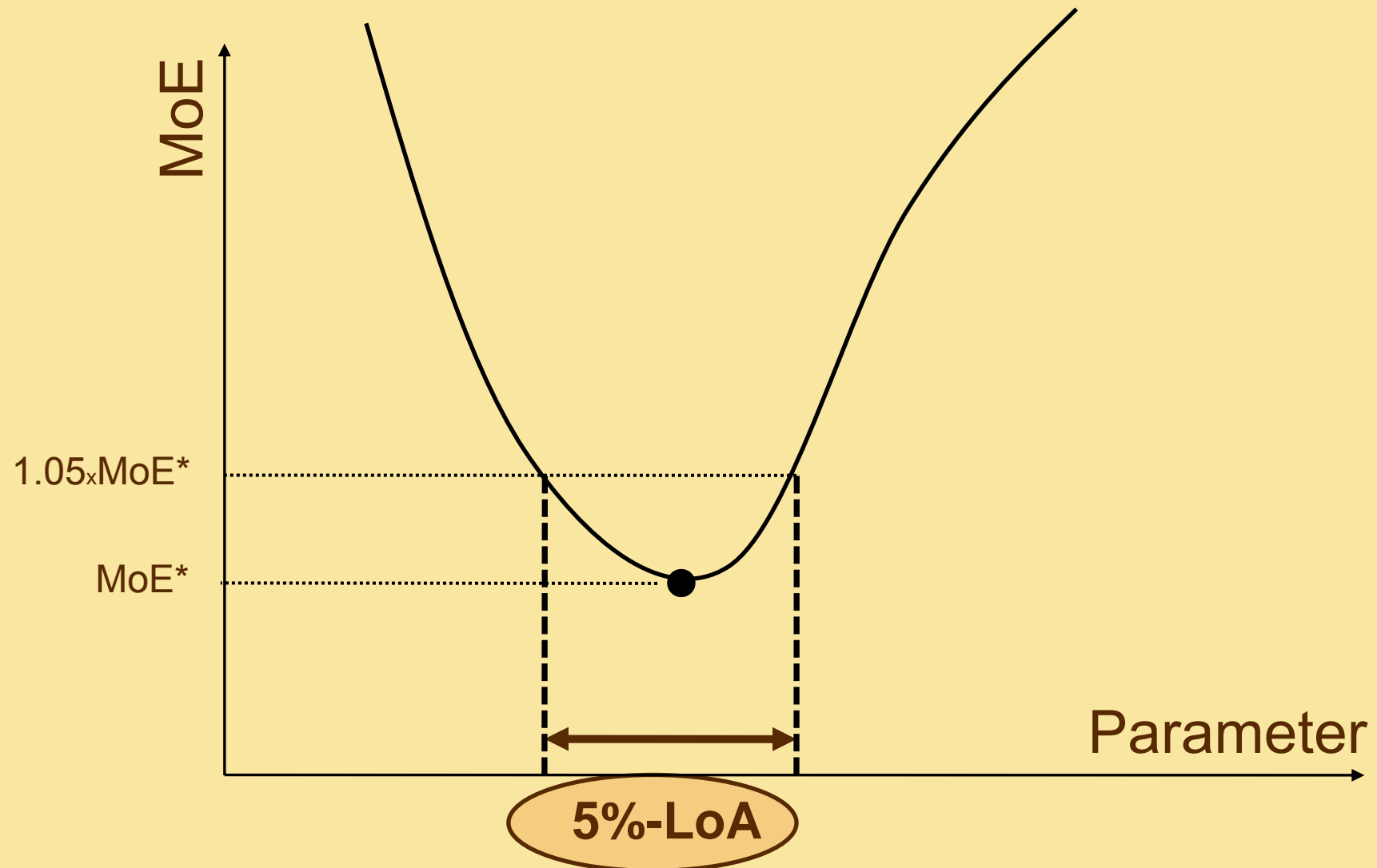
Efficiency?

Accuracy?

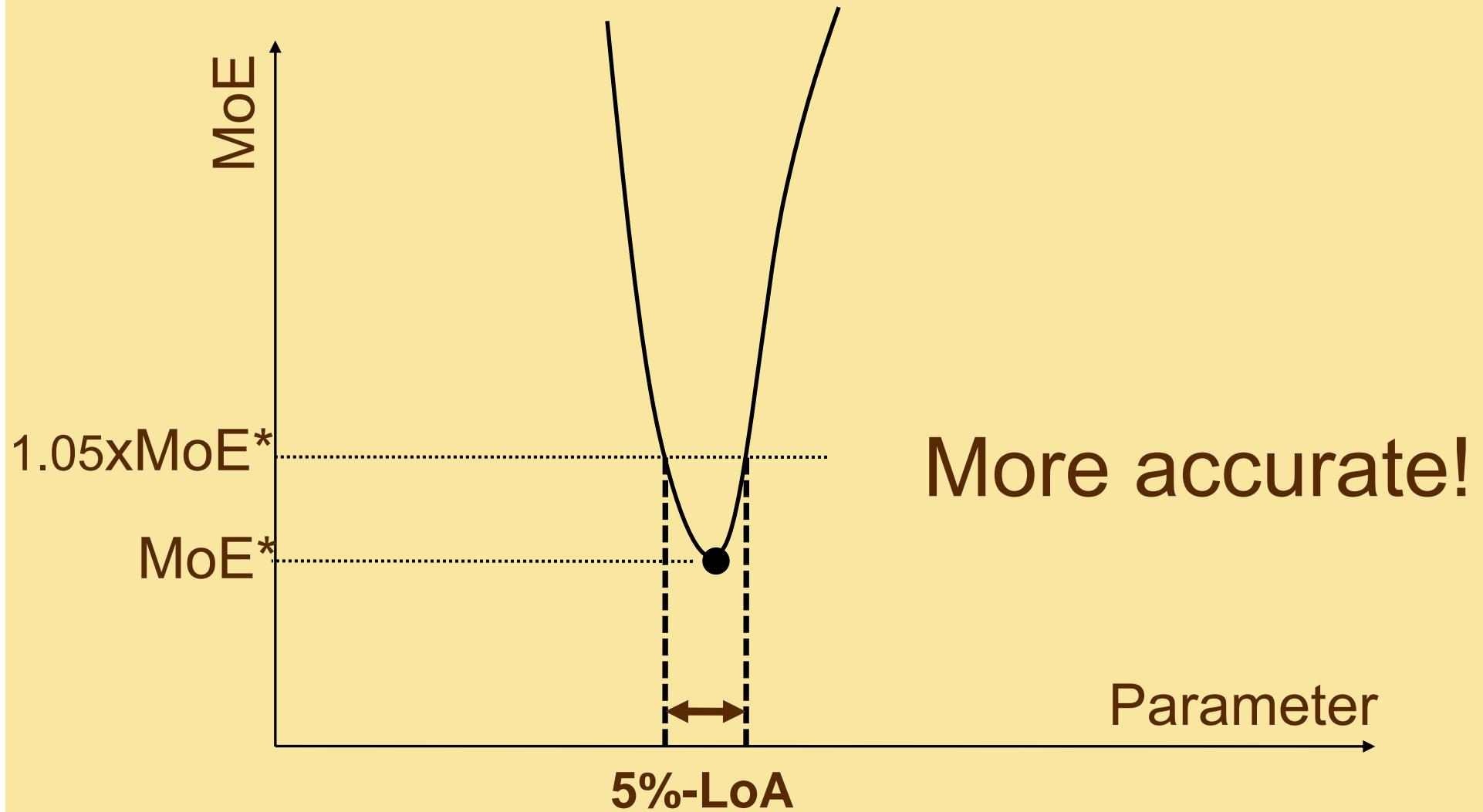
Efficiency



Accuracy



Accuracy



Measurement of variability involved in the car-following rules

Introduction

Methodology

Data

Results

Comparison

	Couple1		Couple2	
	MoE*	LoA ₁ (Interval width)	MoE*	LoA ₁ (Interval width)
First method	1.8m	3.4 m/s	1.2m	4.4 m/s
Second method	11%	2.8 m/s	7%	3.8 m/s

1 : the LoA has been normalized

Measurement of variability involved in the car-following rules

Introduction

Methodology

Data

Results

Comparison

	Couple1		Couple2	
	MoE*	LoA ₁ (Interval width)	MoE*	LoA ₁ (Interval width)
First method	1.8m	3.4 m/s ↕	1.2m	4.4 m/s ↕
Second method	11%	2.8 m/s	7%	3.8 m/s

The second method is more accurate!

1 : the LoA has been normalized

Measurement of variability involved in the car-following rules

Introduction

Methodology

Data

Results

Comparison

	Couple1		Couple2	
	MoE*	LoA ₁ (Interval width)	MoE*	LoA ₁ (Interval width)
First method	1.8m	3.4 m/s	1.2m	4.4 m/s
Second method	11%	2.8 m/s	7%	3.8 m/s

Both methods are more accurate for couple1

1 : the LoA has been normalized

Measurement of variability involved in the car-following rules

Introduction

Methodology

Data

Results

Comparison

	Couple1		Couple2	
	MoE*	LoA ₁ (Interval width)	MoE*	LoA ₁ (Interval width)
First method	1.8m	3.4 m/s	1.2m	4.4 m/s
Second method	11%	2.8 m/s	7%	3.8 m/s

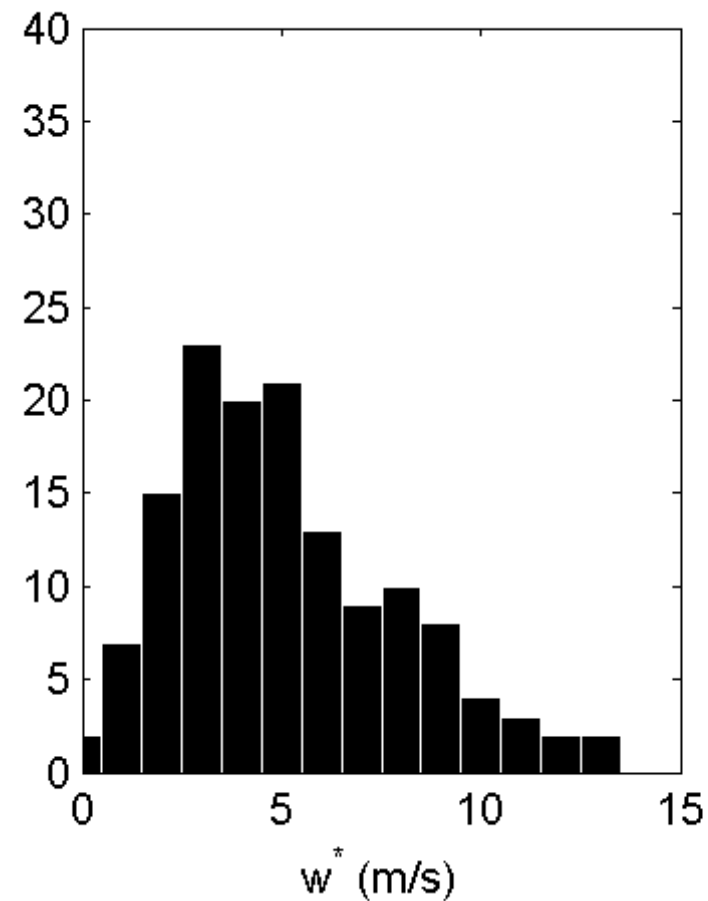
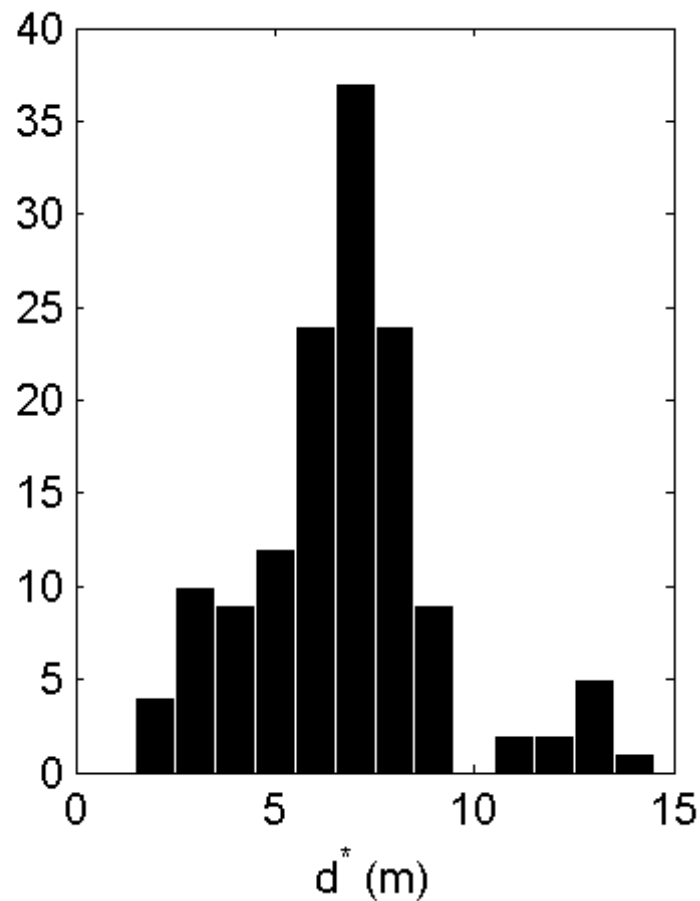
Both methods are more efficient for couple2

1 : the LoA has been normalized

Conclusion

- Identify a simple CF-model consistent with observations
- Explore two methods for estimating individual parameters
- Compare of the results in terms of efficiency and accuracy

Distribution



(method2)

Thank you!!!

REFERENCES

- [Ahn2004] Soyoung Ahn, Michael J. Cassidy and Jorge Laval (2004). *Verification of a simplified car-following theory*. Transp Res. 38B, pp. 431-440.
- [Cassidy1998] Cassidy, M.J. and Windover, J.R. (1998). *Driver memory: motorist selection and retention of individualized headways in highway traffic*. Transp Res. 32A, pp. 129–137.
- [Chiabaut2009a] Chiabaut, N., Leclercq, L. and Buisson, Ch. (2009). From heterogeneous drivers to macroscopic pattern in congestion. Accepted for publication in Transp. Res B.
- [Chiabaut2009b] Chiabaut, N., Buisson, Ch. And Leclercq, L. (2009). Fundamental diagram estimation through passing rate measurements in congestion, accepted to publication in IEEE Transactions on Intelligent Transportation Systems.
- [Duret2008] Duret, A., Buisson, Ch. and Chiabaut, N. (2008). *Estimation individual speed-spacing relationship and assessing the Newell's car-following model ability to reproduce trajectories*. Transportation Research Record.
- [Hoogendoorn2005] Hoogendoorn S.P., and Ossen S. (2005). *Parameter estimation and analysis of car-following models*. Proceedings of the 16th International Symposium on Transportation and Traffic Theory (H.S. Mahmassani, ed.), 2005, pp. 245-265.
- [Newell1993] Newell, G.F. (1993). *A simplified theory of kinematic waves in highway traffic I-General Theory II-Queueing at freeway bottlenecks III-Multi-destination flows*. Transp. Res. 27B, pp. 281–313.
- [Newell2002] Newell, G.F. (2002). *A simplified car-following theory: a lower order model*. Transport. Res. 36B, pp. 195–205.
- [NGSIM] <http://www.ngsim.fhwa.dot.gov/>
- [Ossen2008] Ossen, S. and Hoogendoorn, S., 2008. *Validity of Trajectory-Based Calibration Approach of Car-Following Models in Presence of Measurement Errors*. Transportation Research Board 87th annual meeting 2008, Paper #08-1242, Washington D.C., USA.
- [Ossen2009] Ossen, S. and Hoogendoorn, S., 2009. *Reliability of Parameter Values Estimated Using Trajectory Observations*. Transportation Research Board 88th annual meeting 2009, Paper #09-1898, Washington D.C., USA.